Appels à projets Défi « Transfer Robotique »

Phase 1 - Préprojets sélectionnés

Acronyme	Porteur	Etablissement Chef de file
AMATSUMARA High-precision and long-length robotic assembly	FURET Benoit	Université de Nantes
ANTICOROB Dexterous robotic teleoperating system for painting preparation works	BESSINE Jérome	Commissariat A L'Energie Atomique Et Aux Energies Alternative
ARCANE Autonomous Robot perCeption And Navigation in complex Environments	MARZAT julien	Office national d'études et de recherches aérospatiales
COMFAR Multi sensors command for robotized additive manufacturing	MICHAUD Pierre	Ecole Supérieure des Technologies Industrielles Avancées
DECABOT A cutting-edge service robotics solution for manipulating goods in shops and retail stores in the presence of human workers and customers	MOURET Jean-Baptiste	INRIA
DyMAM Dynamique Microscopic Additive Manufacturing	KROMER Robin	Université de Bordeaux
DYNALOG DYNAmic mission planning and supervision architecture for a large-scale robotised intraLOGistics system	GRAND Christophe	Office National d'Etudes et de Recherches Aérospatiales
Extender Robust, safe and intuitive control for a manipulator arm that can be adapted to the changing needs of people with disabilities	MOREL Guillaume	Sorbonne Université
GORT Generic agnostic robots and data for massive technological agroecological transformations	LABBANI-IGBIDA Ouiddad	Université de Limoges
Grip4all Robotic palletizing of heterogeneous products without prior scheduling	DANEY David	Centre Inria de l'université de Bordeaux
PANDRONE I Airport surveillance and protection through the use of robotics and drones	CHAUMETTE Serge	Université de Bordeaux
PARABOT Towards finishing process by roboted solution 5.0	BIGOT Régis	Ecole Nationale Supérieure d'Arts et Métiers
PARME Robotisation of steel infrastructure maintenance in complex environments	GARNIER Sébastien	Nantes Université

PIRO Potted Insert Robotization	MAGIMEL PELONNIER Vincent	Ecole Supérieure des Technologies Industrielles Avancées
PRECSIX Precise six degree of freedom	UHART Maylist	Ecole Supérieure des Technologies Industrielles Avancées
REISAR Advanced Robotic System for Sewer Network Inspection and Water Preservation	VAUCHEY Vincent	CESI
RoBloc Interchangeable Hardware and Software Modules for Autonomous Aquatic Robots	FABRESSE Luc	Ecole Nationale Supérieure Mines - Télécom Lille Douai
ROLKNEEMATICS Robotics Learning of Knee Implants Real-Time Imagery	KHEDDAR Abderrahmane	Centre National de la Recherche Scientifique
SF30 SLAM France 2030	DANES Patrick	Centre National de la Recherche Scientifique
SOLAR-Nav SOcial Logistics - Advanced Robotic NAVigation	SPALANZANI Anne	Institut national de recherche en sciences et technologies du numérique
SOROSENSE The flexible, user-friendly, accessible and high-performance robot, guardian angel of Quality!	CHERUBINI Andrea	Université de Montpellier
TITANBOT Cable-driven parallel robots for the construction, nuclear and logistics industries	CARO Stéphane	Centre National de la Recherche Scientifique
xHUB eXtra HUB: autonomous logistics platforms	ABBAS-TURKI Abdeljalil	Université de Technologie de Belfort-Montbéliard